

## CHAPTER 8: Rotational Kinematics

*Angular displacement* :  $\Delta\theta = \theta - \theta_0$

$\Delta\theta > 0$  if counterclockwise

$\Delta\theta < 0$  if clockwise

$2\pi \text{ rad} = 1 \text{ revolution} = 360^\circ$

*Average angular velocity* :  $\omega_{avg} = \frac{\Delta\theta}{\Delta t}$

*Average angular acceleration* :  $\alpha_{avg} = \frac{\Delta\omega}{\Delta t} = \frac{\omega - \omega_0}{t - t_0}$

*Equations of rotational motion* :

$$\omega = \omega_0 + \alpha(t - t_0)$$

$$\theta = \theta_0 + \frac{1}{2}(\omega + \omega_0)(t - t_0)$$

$$\theta = \theta_0 + \omega_0(t - t_0) + \frac{1}{2}\alpha(t - t_0)^2$$

$$\omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0)$$

*Tangential quantities :  $\theta, \omega, \alpha$  using radians*

*Arc length :  $s = r\theta$*

*Tangential speed :  $v_T = r\omega$*

*Tangential acceleration :  $a_T = r\alpha$*

*Centripetal acceleration :  $a_c = \frac{v_T^2}{r} = r\omega^2$*

$$a^2 = a_T^2 + a_c^2$$

*Rolling Motion :*

$$d = s$$

$$v = v_T = r\omega$$

$$a = a_T = r\alpha$$